

NAME

CUTEst_cchprods_threaded – CUTEst tool to form the matrix-vector products of a vector with each of the Hessian matrices of the constraint functions.

SYNOPSIS

CALL CUTEst_cchprods_threaded(status, n, m, goth, X, Y, VECTOR, lchp, CHP_val, CHP_ind, CHP_ptr, thread)

DESCRIPTION

The CUTEst_cchprods_threaded subroutine forms the product of a vector with each of the Hessian matrix of the constraint functions $c(x)$ corresponding to the problem decoded from a SIF file by the script *sifdecoder* at the point $x = X$.

The problem under consideration is to minimize or maximize an objective function $f(x)$ over all $x \in R^n$ subject to general equations $c_i(x) = 0$, ($i \in 1, \dots, m_E$), general inequalities $c_i^l \leq c_i(x) \leq c_i^u$ ($i \in m_E + 1, \dots, m$), and simple bounds $x^l \leq x \leq x^u$. The objective function is group-partially separable and all constraint functions are partially separable.

ARGUMENTS

The arguments of CUTEst_cchprods_threaded are as follows:

status [out] - integer

the output status: 0 for a successful call, 1 for an array allocation/deallocation error, 2 for an array bound error, 3 for an evaluation error,

n [in] - integer

the number of variables for the problem,

m [in] - integer

the total number of general constraints,

goth [in] - logical

a logical variable which specifies whether the second derivatives of the groups and elements, and the indexing information held in

CHP_ind and CHP_ptr (see below) have already been set (goth = .TRUE.) or if this information should be computed (goth = .FALSE.),

X [in] - real/double precision

when goth = .FALSE., the Hessians will be evaluated at X. Otherwise X is not used.

VECTOR [in] - real/double precision

an array which gives the vector whose product with the constraint Hessians is required,

lchp [in] - integer

a variable that specifies the declared lengths of CHP_val and CHP_ind. The precise length required may be found by calling *CUTEst_cdimchp* prior to *CUTEst_cchprods_threaded*,

CHP_val [out] - real/double precision

an array that gives the values of the nonzeros in the result obtained by multiplying the constraint Hessians by VECTOR. The values for the i-th constraint are stored in CHP_val(CHP_ptr(i):CHP_val(i+1)-1),

CHP_ind [inout] - integer

an array that gives the indices of the nonzeros in the result obtained by multiplying the constraint Hessians by VECTOR. The indices for the i-th constraint are stored in CHP_ind(CHP_ptr(i):CHP_ptr(i+1)-1), and match the values stored in CHP_val,

CHP_ptr [inout] - integer

an array of length m+1 that gives pointers to the starting positions in CHP_ind and CHP_val for the nonzeros for the product with each Hessian. CHP_ptr(m+1)-1 gives the total space required by CHP_ind and CHP_val.

thread [out] - integer

thread chosen for the evaluation; threads are numbered from 1 to the value threads set when calling CUTEst_csetup_threaded.

NOTE

goth should be set to `.TRUE.` only when a previous call to `CUTEst_cchprods_threaded`, with `goth = .FALSE.`, at the current point has been made. Otherwise, it should be set `.FALSE.`

AUTHORS

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SEE ALSO

CUTEst: a Constrained and Unconstrained Testing Environment with safe threads for mathematical optimization,

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